

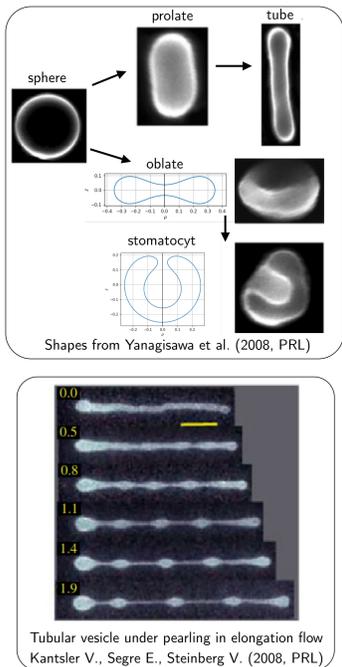
# Dynamics of vesicles under stretching

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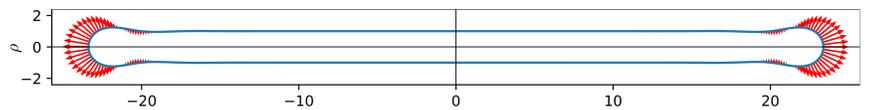
## Introduction

Closed lipid membranes (vesicles), being flexible and incompressible, demonstrate a plethora of non-spherical shapes (especially under simple external influences). Within the framework of the hydrodynamic approach, the bilayer is treated as an infinitely thin liquid film with a surface density of free energy. The starting point for this consideration is Helfrich's energy [W. Helfrich, Z Naturforsch (1973)], which depends on vesicle shape. Corresponding surface forces cause flows in the viscous surrounding liquid. The study investigates the behavior of elongated vesicles under the influence of extending forces, such as uniaxial flow and optical tweezers. There are two critical values of force amplitude: beyond the first, a "dumbbell"-shaped structure forms with a possible infinite elongation, and the second is responsible for the so-called pearling instability, i.e., the formation of beads connected by thin tubes. We also provide a qualitative description of the phenomenon by discussing the variety of stretched shapes and conditions of quasi-stationarity and transition to infinite stretching. In addition, we study the highly nonlinear stage: a slow dynamics remains after the formation of pearls due to the thinness of tubes. Our results qualitatively agree with experimental observations [Kantsler, Segre, and Steinberg (2008)].



## Pearling instability

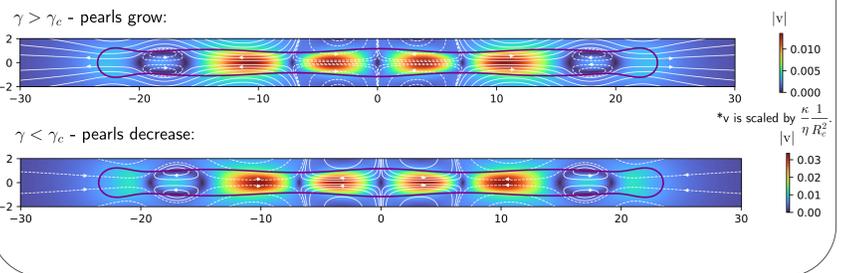
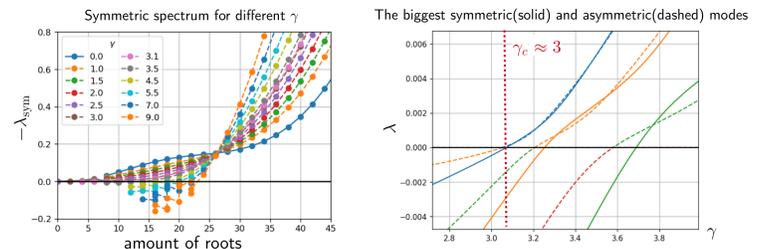
Apply model normal elongating force  $f = \gamma(H - H_0) \Rightarrow$  same state is equilibrium with corrected surface tension  $\delta\sigma = \gamma$



### Linear stability theory

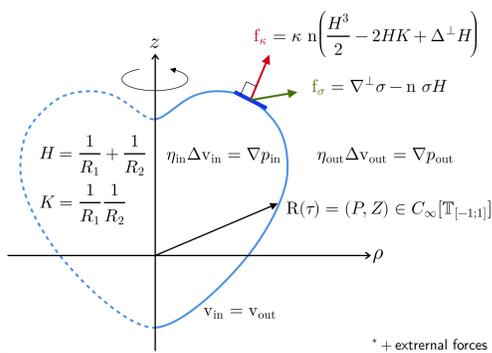
$$R = R_{eq} + \delta R(t) \quad \partial_t R = F[R] \Rightarrow \partial_t \delta R = \frac{\delta F}{\delta R} \delta R = \hat{A} \delta R$$

Find normal modes  $\hat{A} \delta N_k = \lambda_k \delta N_k$  (Locally stable if  $\forall k: \text{Re} \lambda_k < 0$ )



## Governing equation

### Stokes flow, surface forces



### Membrane energies

$$\mathcal{F}_p = \int \frac{K_p}{2} (n/n_0 - 1)^2 dS, \quad K_p \sim 60 \frac{k_B T}{nm^2}$$

$$\mathcal{F}_\kappa = \frac{\kappa}{2} \int H^2 dS + \frac{\kappa}{2} \int K dS, \quad \kappa \sim 20 k_B T$$

$(R/nm)^2 \gg 1 \Rightarrow K_p R^2 \gg \kappa$

Use Green function of Stokes equation to determine velocity, induced by surface forces.

$$v = \int_{S_1} \hat{G}(f_{\kappa 1} + f_{\sigma 1}) \rightarrow v_\mu = \int_{S_1} \tilde{G}_{\mu\nu} f_\nu d\tau$$

Surface tension is 'fast' variable - adiabatic approach

$$\begin{cases} \partial_t n = -v \nabla n - n \nabla^\perp v \\ \sigma \approx -K_p (n/n_0 - 1) \end{cases} \Rightarrow \nabla^\perp v = 0$$

Linear nonlocal equation for  $\sigma$

$$\int_{S_1} (\nabla^\perp \hat{G}) [\nabla^\perp - n_1 H_1] \sigma_1 = -\nabla^\perp v_\sigma$$

Energies are scaled by  $\kappa$ , surface tension  $\sigma$  by  $\kappa/R_0$ , velocity by  $\kappa/\eta R_0^2$ , time by  $\eta R_0^3/\kappa$ , where  $R_0$  - appropriate length scale.

Final scheme  $R \rightarrow f_\kappa \rightarrow v_\kappa \rightarrow \nabla^\perp v \rightarrow \sigma \rightarrow v_\sigma \rightarrow \partial_t R$

## Asymptotic prolate shapes

Conservation of volume and surface area, thus describing by reduced volume  $\mathcal{V} = \frac{V/(4\pi/3)}{(S/4\pi)^{3/2}}$

Prolate vesicles have asymptotic shape: tube with universal edges:

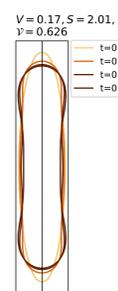
It can be determined as solution of force balance equation, where equilibrium pressure and surface tension can be found using balance far away from edge and scale invariance of Helfrich energy.

$$\begin{cases} \Delta P_{eq} = -\sigma_{eq} H + \kappa (H^3/2 - 2HK + \Delta^\perp H) \\ R \rightarrow R/\lambda \Rightarrow \mathcal{F}_\kappa = \frac{\kappa}{2} \int H^2 dS \rightarrow \mathcal{F}_\kappa \end{cases} \Rightarrow \begin{cases} \sigma_\infty = -\frac{3\kappa}{2r_0^2}, \quad \Delta p_\infty = \frac{2\kappa}{r_0^3} \end{cases}$$

Far away from edge asymptotic:

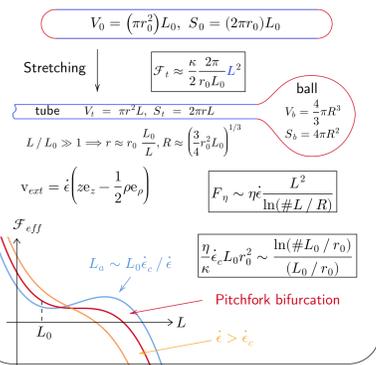
$$P - 1 = \delta P \approx A e^{-\alpha z} \sin(kz + \phi_0), \quad \alpha = \sqrt{\frac{\sqrt{3}-1}{2}}, \quad k = \sqrt{\frac{\sqrt{3}+1}{2}}$$

Convergence to the limit values



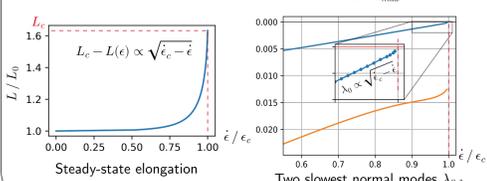
## Infinite elongation transition in extansional flow

### Schematic view:



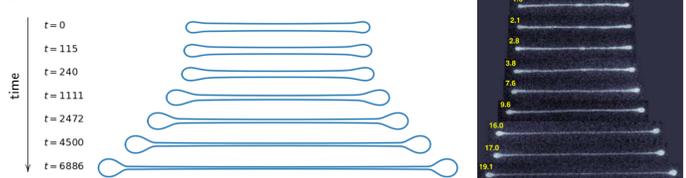
### Under critical $\dot{\epsilon} < \dot{\epsilon}_c$

With a small rate, the vesicle is slightly deformed, while both the length and the shape of the edge change.



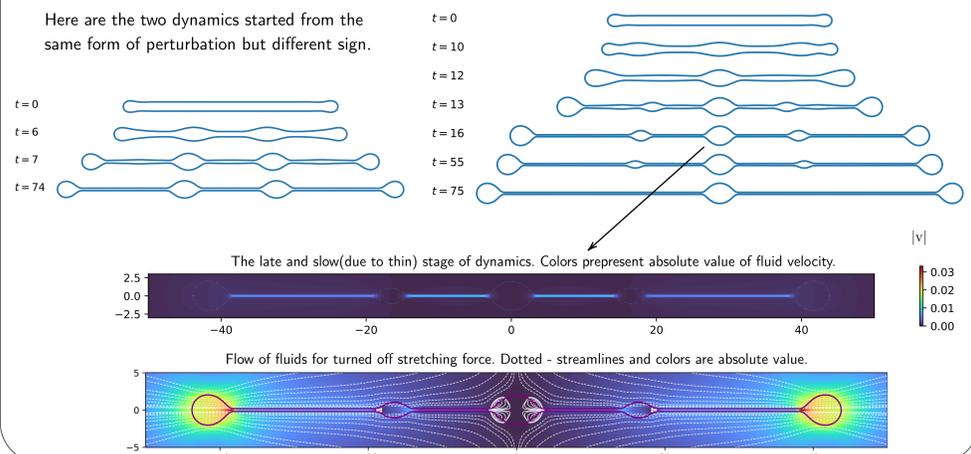
### Upper critical $\dot{\epsilon} > \dot{\epsilon}_c$

When the rate is above the critical value, the vesicle goes into unlimited stretching. On the right are the frames of our simulation and the experimental data from Kantsler V., Segre E., Steinberg V. (2008, PRL)



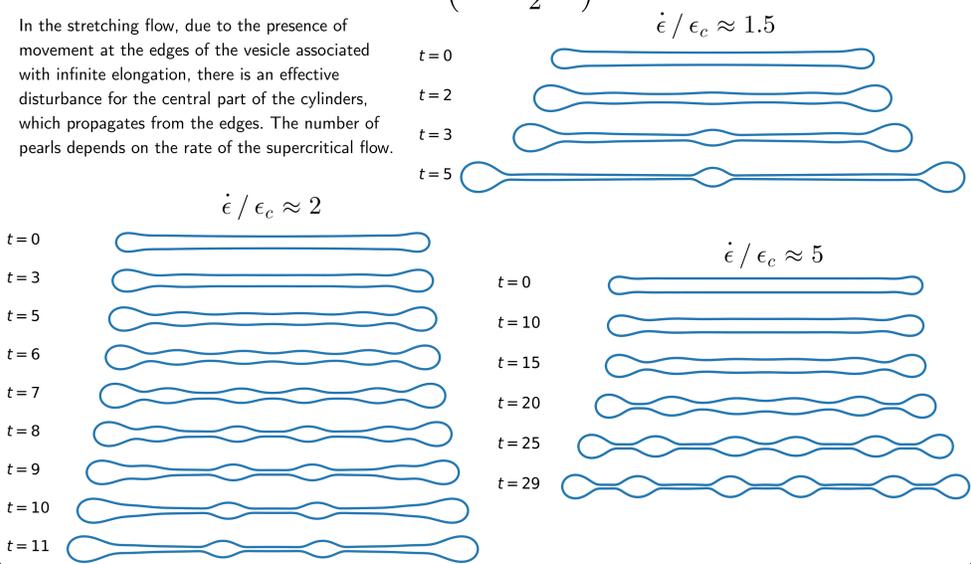
## Development of the most unstable mode

Here are the two dynamics started from the same form of perturbation but different sign.



## Instability in extensional flow $v_{ext} = \dot{\epsilon} \left( ze_z - \frac{1}{2} \rho e_\rho \right)$

In the stretching flow, due to the presence of movement at the edges of the vesicle associated with infinite elongation, there is an effective disturbance for the central part of the cylinders, which propagates from the edges. The number of pearls depends on the rate of the supercritical flow.



## Conclusion

We developed a reliable algorithm for modeling the nonlinear dynamics of closed axially symmetric vesicles. Asymptotic shape and equilibrium parameters for elongated vesicles were derived. The infinite elongation transition in extensional flow were analyzed numerically and analytically. The "pearling instability" under the action of tensile forces applied to the edges of the vesicle and in strong extensional flow were considered; force critical values were obtained. We simulated the development of instability in a nonlinear regime with "pearls" formation and disappearing during slow late stage of dynamics.

## Acknowledgements

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